

touché Is Required for Touch-Evoked Generator Potentials within Vertebrate Sensory Neurons

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The process by which light touch in vertebrates is transformed into an electrical response in cutaneous mechanosensitive neurons is a largely unresolved question. To address this question we undertook a forward genetic screen in zebrafish (*Danio rerio*) to identify mutants exhibiting abnormal touch-evoked behaviors, despite the presence of sensory neurons and peripheral neurites. One family, subsequently named *touché*, was found to harbor a recessive mutation which produced offspring that were unresponsive to light touch, but responded to a variety of other sensory stimuli. The optogenetic activation of motor behaviors by *touché* mutant sensory neurons expressing channelrhodopsin-2 suggested that the synaptic output of sensory neurons was intact, consistent with a defect in sensory neuron activation. To explore sensory neuron activation we developed an *in vivo* preparation permitting the precise placement of a combined electrical and tactile stimulating probe upon eGFP-positive peripheral neurites. In wild-type larva electrical and tactile stimulation of peripheral neurites produced action potentials detectable within the cell body. In a subset of these sensory neurons an underlying generator potential could be observed in response to subthreshold tactile stimuli. A closer examination revealed that the amplitude of the generator potential was proportional to the stimulus amplitude. When assayed *touché* mutant sensory neurons also responded to electrical stimulation of peripheral neurites similar to wild-type larvae, however tactile stimulation of these neurites failed to uncover a subset of sensory neurons possessing generator potentials. These findings suggest that *touché* is required for generator potentials, and that cutaneous mechanoreceptors with generator potentials are necessary for responsiveness to light touch in zebrafish.

Introduction

The identification of mechanosensitive proteins in vertebrates using traditional approaches, such as affinity purification and expression cloning, has been hampered by the lack of high-affinity ligands and the likelihood that the mechanosensitive proteins must be coexpressed with additional membrane and cytoskeletal elements to function properly. Thus many researchers have looked to organisms amenable to forward genetic

screens, such as *Caenorhabditis elegans* and *Drosophila*, in the hopes of identifying mechanosensitive proteins conserved across evolution. However many of the candidate proteins identified from screens in these invertebrate organisms (Colbert and Bargmann, 1995; Walker et al., 2000; Liedtke et al., 2003; O'Hagan et al., 2005; Kindt et al., 2007) have been shown to be unessential for light touch in vertebrates (Sidi et al., 2003; Suzuki et al., 2003; Drew et al., 2004; Bautista et al., 2006; Kwan et al., 2006). These results raise the possibility that the proteins that mediate mechanotransduction in touch-sensitive neurons may not be conserved across phylogeny. Therefore we and others have turned to zebrafish (Granato et al., 1996; Haffter et al., 1996), a vertebrate model organism amenable to both genetic and *in vivo* electrophysiological manipulations.

Zebrafish embryos develop externally, possess a relatively simple nervous system, and respond to tactile stimuli within the first day of development (Saint-Amant and Drapeau, 1998). The neurons that activate touch-evoked behaviors are segregated into two groups: trigeminal ganglia neurons relay tactile stimuli delivered to the craniofacial region (Sneddon, 2003), and Rohon-Beard (RB) neurons within the spinal cord that relay tactile stimuli to the trunk and tail regions (Clarke et al., 1984). Both groups of neurons are likely polymodal as they have been shown to exhibit differential expression of several receptors implicated in nociception (Cockayne et al., 2000, 2005; Kucenas et al., 2003), and ubiquitous expression of TRPA1b which is essential for re-

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sponsiveness to the noxious compound mustard oil (Prober et al., 2008).

In a previous study, the membrane properties of RB neurons from several potential mechanosensitive mutants were chosen for detailed electrophysiological analysis (Ribera and Nüsslein-Volhard, 1998). Results from this study revealed that most mutant sensory neurons possessed defects within their excitable properties, and therefore are not strong candidates for mutations affecting mechanosensation. Recognizing the need for additional touch-unresponsive mutants we undertook another forward genetic screen to identify novel mutants with abnormal touch-evoked behaviors. From our screen one family (*mi173*), subsequently named *touché* (*mi173*), was found to harbor a recessive mutation which resulted in offspring that were selectively unresponsive to light touch. Employing a novel *in vivo* recording technique we failed to uncover a subset of sensory neurons in *touché* mutants which responded to tactile stimulation with generator potentials. These findings indicate that *touché* is required for generator potentials, and that sensory neurons with generator potentials underlie responsiveness to light touch in zebrafish.

Materials and Methods

Animal care and use. Zebrafish were bred and raised according to approved guidelines set forth by the Animal Experimentation Ethics Committee, Université de Montréal and the University Committee on Use and Care of Animals, University of Michigan. Staging of embryos was performed as described previously (Kimmel et al., 1995). The *touché* allele *mi173* (*mi173*) was identified in a screen conducted at the University of Michigan, Ann Arbor following previously published procedures (Haffter and Nüsslein-Volhard, 1996).

Mapping. A mapping family for *touché* was established by crossing a *touché* male carrier (Michigan genetic background) with a wild-type WIK female (Zebrafish Resource Center, Eugene, Oregon). Offspring from this mapping family were subjected to bulk segregate analysis (Postlethwait et al., 1994) according to the Zon laboratory protocol (<http://zfrhmaps.tch.harvard.edu>) using 20 wild-type sibling and 20 *touché* mutants.

Behavioral analysis. All reagents were obtained from Sigma-Aldrich unless otherwise noted. Embryos at ~24 h postfertilization (hpf) were dechorionated with pronase, staged and segregated according to their responsiveness to touch. Tactile and nociceptive stimuli were delivered by striking the tail of an embryo with a sideways motion up to 3 times with a pair of No.5 forceps and pinching of the tail, respectively. The speed of tactile stimuli was assessed offline by measuring tip displacement (Fig. 1A) as a function of time. Embryos were exposed to noxious stimuli individually in 24 well plates: allyl-isothiocyanate (Acros Organics) at 500 μ M mustard oil in sham (1% DMSO, v/v in Evans solution), or acidified Evans solution (pH 4.5 adjusted with acetic acid, sham Evans, pH 7.5).

Electrically evoked bouts of swimming used in the stopping assay were elicited using a bipolar electrode and an A-M Systems Model 2100 isolated pulse stimulator in larvae embedded in 1% (w/v) low-melting point agarose. To mimic head-first collisions a jet of water was applied to the head (20 psi, 50 ms) using a Picospritzer III (Parker Hannifin). The electrical stimulus was paired with an LED (see Fig. 3A), and the timing of

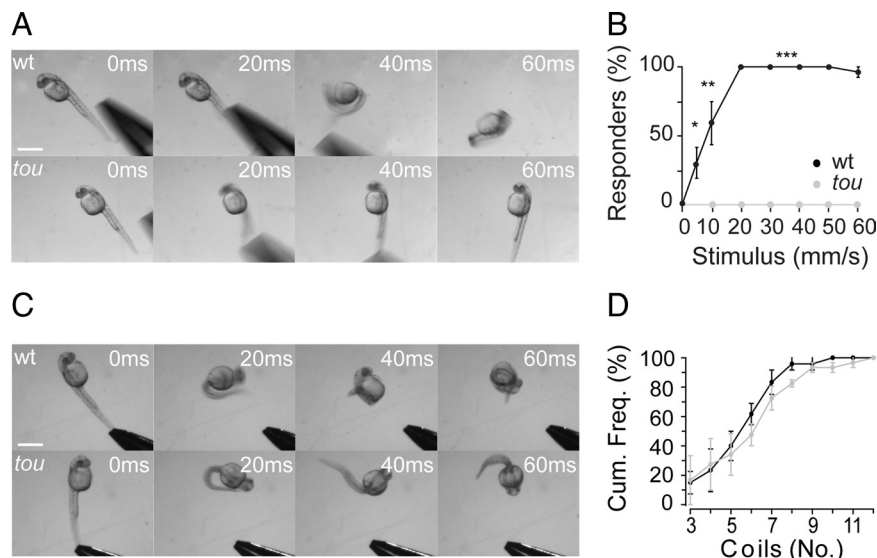


Figure 1. *touché* mutants fail to respond to light touch, but respond to tail-pinching. **A**, Time-lapse images of responses to tactile stimuli applied to the tail of a 26 hpf embryos. **B**, Correlation of tactile stimuli speed and the percentage of responsive wild-type and *touché* mutant embryos (Each speed $n = 15$ embryos from 3 clutches). Values here and in subsequent figures represent the average \pm SEM. p values here and in subsequent figures are as follows: $*p < 0.05$, $**p < 0.01$, $***p < 0.001$. **C**, Pinching of the caudal fin (nociceptive tail-pinching) evoked coiling in both wild-type and *touché* mutants. **D**, Cumulative frequency of the number of coils performed in response to tail-pinch ($n = 15$ embryos from 3 clutches). Scale bars: **A**, **C**, 500 μ m.

both was controlled by pClamp 8 software using a Digidata 1200 interface (Molecular Devices).

Acoustic-vestibular responses were assayed between 2 and 4 d postfertilization (dpf). At 2 dpf the ability of lateral-line stimuli to activate motor behaviors was examined by placing larvae individually into the center of a 60 mm dish in 3 ml of fish water (Westerfield, 2000). To the side of the dish was added 1 ml of fish water by pipette to cause passive displacement of the larvae. Larvae were scored as positive responders if motor activity was observed before the larvae stopped moving passively. The contribution of inner-ear hair cell function to body posture was assayed at 3 dpf by counting the number of dorsal-up orientated larva. The ability to respond to acoustic stimuli was assayed by placing larvae into 60 mm dishes in 4 ml of fish water atop a metal plate. The plate was sharply struck with a metal rod from a constant height to cause a loud audible sound. Some experiments were performed on the mutants and siblings simultaneously to rule out subtle changes in threshold for detection.

Light-evoked (480 nm) activation of motor behaviors was performed by injecting 50 pg of plasmid containing channelrhodopsin-2 coupled to enhanced yellow fluorescent protein (ChR2-eYFP) under the control of the Isl1-SS-enhancer:Gal4-VP16:UAS-E1b promoter (Douglass et al., 2008) diluted in 5 nl of water containing 0.01% phenol red into freshly fertilized embryos from *touché* carrier in crosses at the 1–2 cell stage using a Nanoinject II system (Drummond Scientific). Embryos were screened at ~24–27 hpf for expression eYFP and touch responsiveness using an Olympus dissecting microscope (SZX7) fitted with epifluorescence. Light-evoked motor behaviors were triggered manually by opening a shutter on individual embryos in 24 well plates.

Behaviors were recorded at 30 and 200 Hz using Flea2 (FL2-20S4M-C) and Grasshopper (GRAS-03K2M-C) cameras from Point Gray (Richmond, BC). Images were captured with PRG Flycap, and analyzed offline using ImageJ (<http://rsbweb.nih.gov/ij/>).

FM1-43 dye uptake and immunohistochemistry. For dye uptake FM1-43 (Invitrogen), a dye thought to enter hair cells through the mechanotransduction channel, was applied at 3 μ M in Evans solution (see below) for 30 s. Thereafter, larvae were washed in Evans solution containing the local anesthetic tricaine (0.02% w/v) five times for 10 s each. Dye uptake was assessed on a dissecting microscope fitted with a QICAM Fast 1394 camera from QImaging.

For labeling eGFP and ChR2-eYFP larvae were fixed in 4% paraformaldehyde for 30 min and then washed five times for 10 min in washing

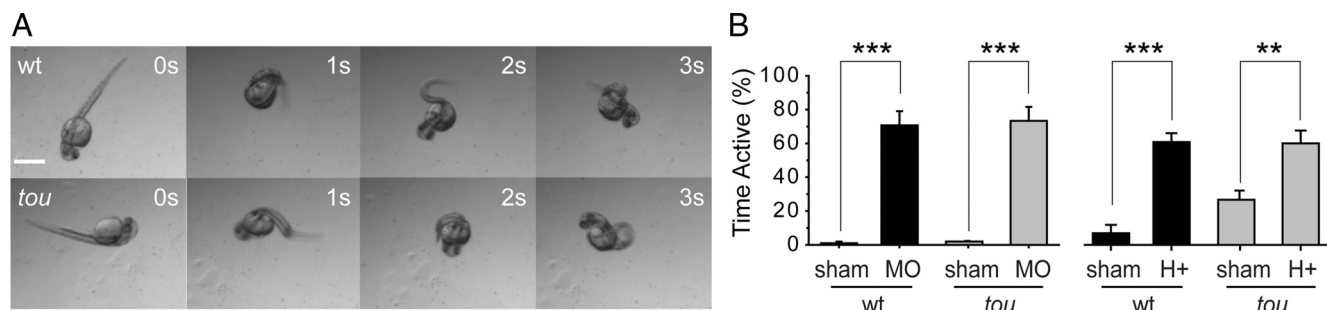


Figure 2. *touché* mutants respond normally to noxious stimuli. **A**, Time-lapse images of wild-type and *touché* mutant motor behaviors in the presence of mustard oil (500 μ M) at 26 hpf. Scale bar, 500 μ m. **B**, Analysis of percentage time active within the first 10 s of exposure to mustard oil (MO; $n = 28$ embryos from 3 clutches), and within 10 s following 1 min of exposure to low pH (H+; $n = 15$ embryos from 3 clutches; images not shown) compared with sham controls for mustard oil (1% DMSO) and low pH (Evans solution, pH 7.5), respectively. ** $p \leq 0.01$, *** $p \leq 0.001$.

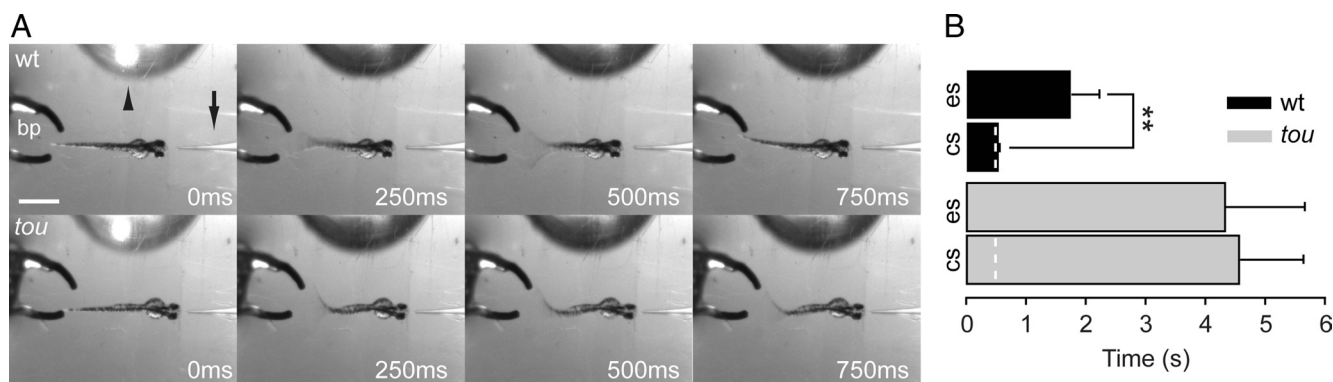


Figure 3. *touché* mutants lack a stopping response. **A**, Time-lapse images of wild-type and *touché* mutants at 48–52 hpf during electrically evoked swimming trials wherein the counterstimulus was applied. The electrical stimulus delivered by a bipolar probe (bp) was paired with an LED (arrowhead) visible within the field of view. The counterstimulus, waterjet (arrow), was applied 500 ms following the electrical stimulus. Scale bar, 500 μ m. **B**, Time spent swimming following the electrical stimulus (es) alone, or in trials where the counterstimulus (cs) was applied. The counterstimulus is indicated as a dashed line ($n = 10$ larvae for each from 3 clutches). ** $p \leq 0.01$.

buffer (PBS containing 0.1% Triton X-100), and two times for 10 min in blocking buffer (wash buffer containing 2 mg/ml bovine serum albumin). Rabbit anti-EGFP (Torrey Pines Biolabs) primary was diluted 1/1000 in blocking buffer and bound overnight. Thereafter larvae were washed five times for 10 min in washing buffer, two times for 10 min in blocking buffer. Secondary antibody (anti-rabbit Alexa-488, Invitrogen) diluted 1/1000 in blocking buffer was bound for 4 h. Larvae were then washed five times for 10 min with washing buffer and then mounted in 70% glycerol in PBS. Images were captured with a spinning disk confocal (Quorum) microscope (Olympus, BX-51). Three segments above the anus were analyzed for RB cell counts. For trigeminal neuron cell counts the average diameter of a trigeminal neuron was first determined to be $\sim 8 \mu$ m. Optical stacks of trigeminal ganglia were then divided into 8 μ m optical sections, starting 4 μ m into the ganglion, and neurons with discernable cell bodies were counted under double blind conditions. Innervation of the skin by peripheral neurites was determined by thresholding all neurite projections in the skin for the 3 somites centered on the anal somite under double blind conditions. Thereafter the percentage of the total thresholded area relative to total area was determined using ImageJ.

Recording methods. Electrophysiological recordings from zebrafish were obtained from neurons at room temperature using methods similar to those previously described (Hamill et al., 1981; Ribera and Nüsslein-Volhard, 1998; Drapeau et al., 1999). In brief larvae were anesthetized in Evans recording solution (in mM): 134 NaCl, 2.9 KCl, 2.1 CaCl₂, 1.2 MgCl₂, 10 glucose, 10 HEPES, pH 7.5 with NaOH containing 0.02% (w/v) tricaine. The skin of a larva pinned to a 35 mm Sylgard-coated dish was removed with a pair of No.5 forceps. The solution was exchanged with Evans solution containing 15 μ M curare flowing throughout the recording session at ~ 1 ml/min. To gain access to the spinal cord the bath solution was replaced with recording solution containing 4 mg/ml collagenase type XI and incubated until the muscle started to separate (~ 10 min). Thereafter the muscle was peeled away using suction applied to a

broken pipette ($\sim 50 \mu$ m). The internal recording solution contained the following (in mM): 116 K-gluconate, 16 KCl, 2 MgCl₂, 10 HEPES, 10 EGTA, at pH 7.2 with KOH and 0.1% SulforhodamineB for cell type identification. Borosilicate glass electrodes had resistances of 5–8 M Ω when filled with internal recording solution. Recordings were made with an Axopatch 200B amplifier (Molecular Devices) low-passed filtered at 1–5 kHz and sampled at 1–10 kHz. Electrical and tactile stimuli were delivered through the use of a bipolar stimulating probe (A-M Systems Model 2100) controlled by a piezoelectric stimulator (Moffatt and Hume, 2007). Probes were placed upon eGFP-positive neurites $\sim 100 \mu$ m from the cell body. Generator potential amplitudes were normalized for RB cell input resistance, and scaled to zero which represents the displacement preceding the first observable membrane depolarization as described previously (Drew et al., 2002). Data acquisition was controlled by pClamp 10 software using a Digidata 1440A interface. The initial data analysis was done with Clampfit 10, and figures were prepared using SigmaPlot 11.0.

Results

touché is a novel light touch-unresponsive mutant

In contrast to other organisms a clear difference between light touch and nociceptive stimuli, and their related behavioral responses, has not been defined for zebrafish. In an attempt to address this deficit we first examined the behavioral responsiveness of zebrafish embryos to increasing forces delivered by calibrated animal hairs and commercially available von Frey filaments. However the lowest hairs and filaments obtainable (~ 5 – 8 mg) consistently resulted in the activation of motor behaviors in zebrafish embryos. As work from other organisms predicted that zebrafish embryos might display a graded responsiveness to increasing forces we reasoned that ~ 5 mg was greater

than the minimal force detectable by zebrafish embryos. Therefore we explored whether varying the speed at which a tactile stimulus was delivered might uncover speeds, and related forces at which zebrafish embryos exhibited a graded responsiveness to tactile stimuli. In response to stimuli below 5 mm/s all zebrafish embryos failed to respond to touch (Fig. 1*A,B*). Increasing the speed of delivery resulted in a corresponding increase in the percentage of responsive embryos, until at 20 mm/s when all embryos examined were responsive. Closer examination also revealed that the maximum number of coils performed by zebrafish embryos in response to light touch was three.

To elicit a more nociceptive response the tips from a pair of forceps were closed upon the caudal fin, herein referred to as tail pinching (Fig. 1*C*). In response to tail pinching, zebrafish embryos were found to consistently perform 3 or more coils, with a range of 3–12 coils (Fig. 1*D*). Thus zebrafish embryos exhibit at least two different levels of responses to increasing forces, with light touch stimuli evoking ≤ 3 coils and nociceptive stimuli evoking ≥ 3 coils.

In a screen for novel zebrafish mutants exhibiting abnormal touch-evoked motor behaviors one family (*mi173*), subsequently named *touché* (*mi173*), was found to harbor a recessive mutation which resulted in offspring that were unresponsive to light touch (Fig. 1*A,B*), but retained the ability to respond to tail-pinching (Fig. 1*C,D*). To determine whether *touché* represented a new touch-unresponsive mutant we rough mapped the *touché* locus to chromosome 2. Of the previously identified touch-unresponsive mutants (Granato et al., 1996) only *macho* (*mao*^{tt261}) has been mapped to chromosome 2 (www.zfin.org), and therefore complementation analysis was performed with *macho*. Pair-wise crosses between *macho* and *touché* complemented the mutant phenotypes indicating that *touché* is not a new allele of *macho*. Collectively these findings indicate that *touché* represents a new touch-unresponsive mutant, deficient in the ability to respond light touch.

touché mutants are responsive to multiple noxious stimuli

The finding that *touché* mutants were unresponsive to light touch, but responded to tail-pinching prompted an investigation into the responsiveness of *touché* mutants to other modes of sensory stimuli. During the first few days of development, zebrafish are responsive to the compound commonly known as mustard oil (allyl-isothiocyanate) and to low pH. The behavioral responsiveness of zebrafish to mustard oil was shown to require TRPA1b, a member of the TRP superfamily of cation channels

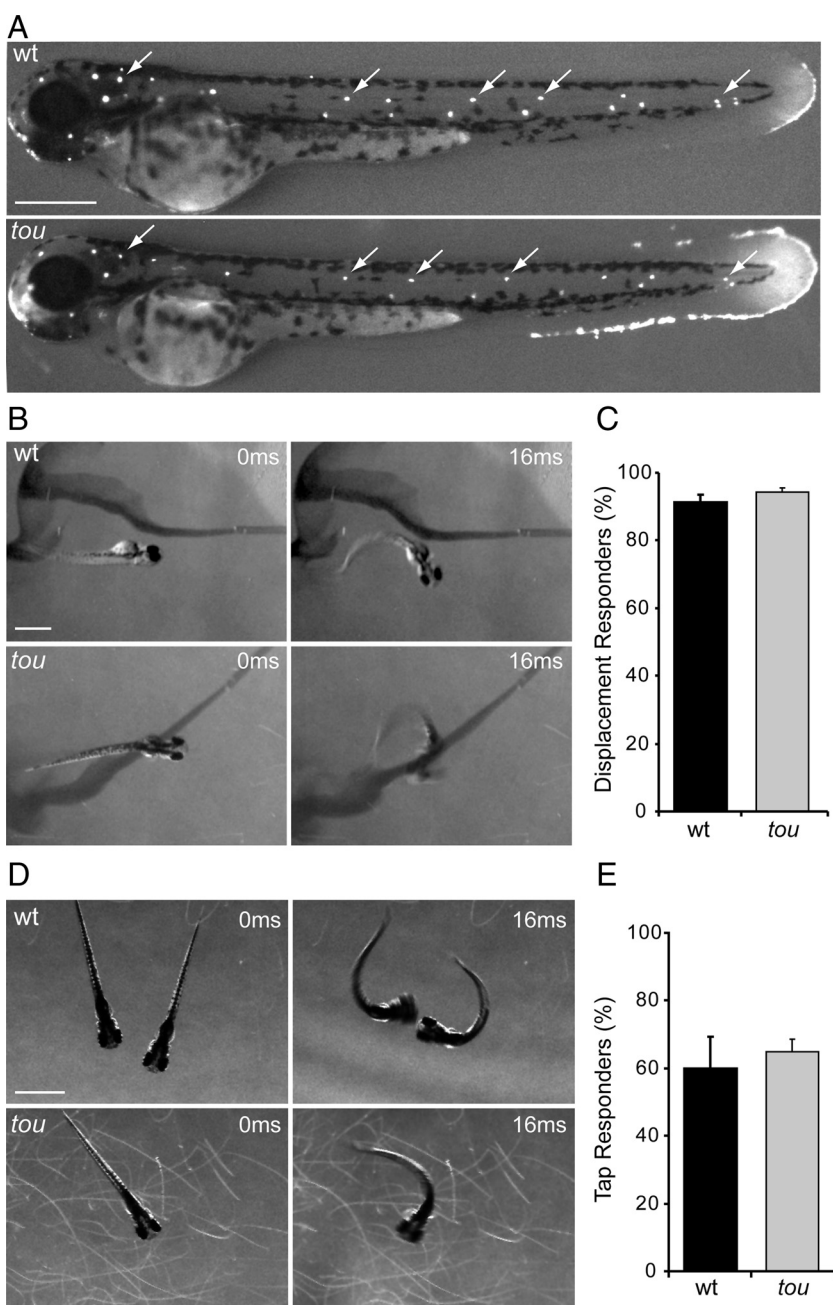


Figure 4. *touché* mutants respond to acoustic-vestibular stimuli. **A**, FM1-43 dye uptake by hair cells of the lateral-line (arrows indicate the location of hair cells within a few neuromasts) is present in both wild-type and *touché* mutants 48–52 hpf. Of note black regions are melanophores, and whitening along the caudal fin is background dye labeling. Scale bar, 200 μ m. **B**, Time-lapse images of wild-type and *touché* mutant larvae 48–52 hpf. A lateral line stimulus (rapid water flow, dark stream) was delivered along the body axis. Scale bar, 500 μ m. **C**, Responsiveness of wild-type ($n = 99$ from 4 clutches) and *touché* mutants to lateral-line stimuli ($n = 92$ from 4 clutches). **D**, Time-lapse images of responses of wild-type and *touché* mutant larvae 96–100 hpf to tapping of the dish. Scale bar, 1 mm. **E**, Responsiveness of wild-type and *touché* mutants to dish tapping ($n = 80$ from 4 clutches for each).

expressed by zebrafish sensory neurons (Prober et al., 2008). To examine the responsiveness of wild-type and *touché* mutants to mustard oil, embryos were transferred into Petri dishes preloaded with mustard oil. Under control conditions (Evans solution containing 1% DMSO) wild-type and *touché* mutants were found to be predominantly inactive (Fig. 2*A,B*). However when exposed to mustard oil wild-type and *touché* mutants were both significantly more active. Comparisons failed to uncover a significant difference in the time active in mustard oil between wild-type and *touché* mutants.

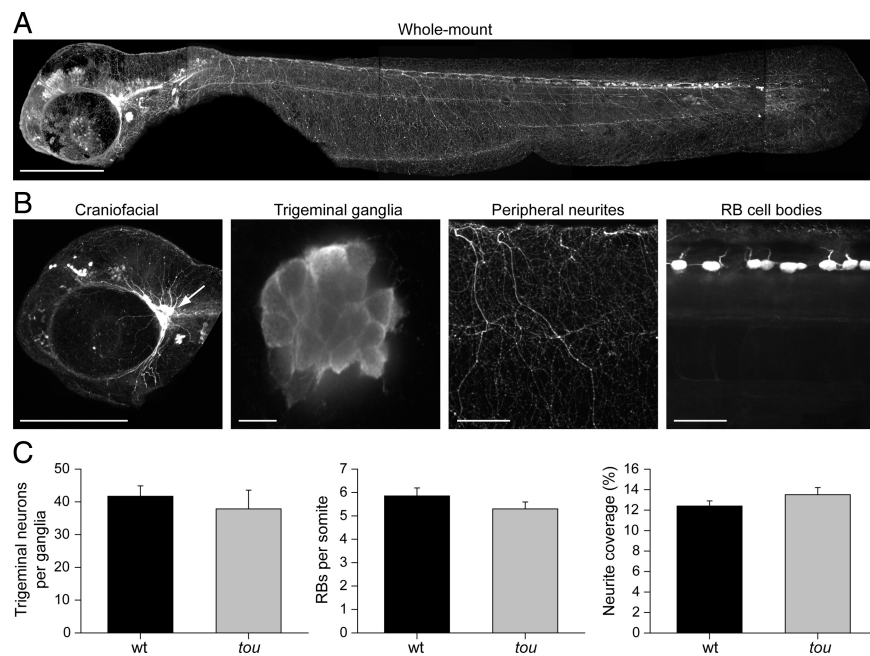


Figure 5. Gross morphology of sensory neurons in *touché* mutants appears normal. **A**, Whole-mount labeling of eGFP-positive sensory neurons from a *touché* mutant larvae at 52 hpf; scale bar, 200 μ m. **B**, Craniofacial labeling with trigeminal ganglia highlighted (arrow); scale bar, 200 μ m. Trigeminal ganglia; scale bar, 10 μ m. Peripheral neurites; scale bar, 50 μ m. RB cell bodies; scale bar, 50 μ m. **C**, Average trigeminal neurons per ganglia, RBs per somite, and coverage of skin by peripheral neurites ($n = 9$ for each, from 3 clutches).

In contrast to mustard oil, the process by which low pH is perceived by zebrafish and transformed into a behavioral response is unknown. However it is likely to involve member(s) of the acid sensing ion channel (ASIC) family and/or TRPV1, which are known to be expressed by a subset of sensory neurons in zebrafish (Paukert et al., 2004; Caron et al., 2008). To determine whether *touché* mutants were capable of perceiving and responding to low pH we exposed larvae to acidified Evans recording solution, pH 4.5. When compared to normal Evans (pH 7.5), wild-type and *touché* mutants were both found to be significantly more active (Fig. 2B). Comparisons of time active between wild-type and *touché* mutants again failed to uncover a significant difference. Thus *touché* is not required for the behavioral responsiveness to these noxious stimuli.

touché mutants lack a stopping response

After the onset of swimming it was noted that *touché* mutants often failed to stop swimming upon head-first collisions with the sides of dishes. This “stopping response” has been shown to require feedback from mechanosensitive trigeminal neurons in *Xenopus laevis* embryos (Boothby and Roberts, 1992a,b). To examine this finding in detail, larvae were restrained in agar, with the tail and head regions exposed to allow for the delivery of stimuli and swimming. Larvae were then induced to swim by passing a current across the caudal tail using a bipolar stimulating electrode (Fig. 3A), which has been shown to activate zebrafish sensory neurons *in vivo* (Higashijima et al., 2003). In an equal number of trials a puff of water referred to as the counterstimulus was delivered to the head 500 ms after an electrical stimulus. In wild-type larvae the counterstimulus resulted in a significant reduction in the duration of swimming (Fig. 3B). In contrast, no significant reduction in the duration of swimming was observed in *touché* mutants following the counterstimulus. Therefore *touché* mutants lack two sensory-evoked behaviors known to require input from mechanosensitive neurons.

touché mutants respond to acoustic-vestibular stimuli

To rule out a wholesale disruption of mechanosensitive process in *touché* mutants, we assayed behaviors dependent upon input from mechanosensitive hair cells of the inner ear and the lateral-line. Mechanotransduction within these hair cells allow zebrafish to respond to water displacement, acoustic stimuli (tapping), and contribute to a dorsal-up body posture. As a first level of characterization of mechanotransduction within these hair cells, we exposed embryos to the dye FM1-43, which is thought to enter hair cells through the mechanotransduction channel (Seiler and Nicolson, 1999). Following incubation in FM1-43, wild-type and *touché* mutant hair cells both exhibited uptake of the fluorescent dye (Fig. 4A).

Behavioral defects mediated by mutations in proteins essential to the function of the lateral-line and inner ear hair cells become obvious between the second and fourth days of development (Nicolson et al., 1998). When assayed, no differences in the responsiveness to water displacement (Fig. 4B,C), or tapping (Fig. 4D,E) were found between wild-type and *touché* mutants. Similarly wild-type and *touché* mutants were both found to be dorsally orientated on day 4 (Fig. 4B,D). Thus mechanotransduction within *touché* mutant hair cells appears present, indicating that the *touché* mutation does not affect all mechanically sensitive cells.

Sensory neuron anatomy in *touché* mutants

The behavioral results thus far suggest a role for *touché* within touch-sensitive neurons. This role could be functional, such as in the relay of tactile stimuli to second order neurons. Alternatively *touché* could be required developmentally for the differentiation and/or retention of touch-sensitive neurons. As a first step in distinguishing between these two possibilities, the presence and morphology of sensory neurons in zebrafish were compared between wild-type and *touché* mutants. In zebrafish, tactile stimuli are conferred by two groups of touch-sensitive neurons: trigeminal neurons relay touch to the craniofacial region and RB cells relay touch to the trunk and tail regions. To facilitate the identification and characterization of trigeminal neurons and RB cells, the *touché* mutation was crossed into a stable transgenic line (Uemura et al., 2005) expressing eGFP under the control of a sensory neuron enhancer-promoter (*ssx-mini-ICP:eGFP*). When compared with wild-type siblings, *touché* mutants were found to possess a similar number of RB cells per somite, trigeminal neurons per ganglia, and an indistinguishable amount of neurite coverage by sensory neurons (Fig. 5). Thus there does not appear to be a gross morphological difference between the sensory neurons of wild-type and *touché* mutants.

Light-evoked activation of sensory neurons triggers motor behaviors in *touché* mutants

Given that sensory neurons appear normal in *touché* mutants we examined whether the exogenous activation of sensory neurons could trigger motor behaviors. Recently, exposure to blue light in embryos expressing ChR2-eYFP under the control of a sensory

neuron promoter was shown to be sufficient to trigger action potentials within trigeminal neurons, and activation of motor behaviors (Douglass et al., 2008). The injection of the ChR2-eYFP construct resulted in embryos with several fluorescent cells in locations consistent with sensory neurons (Fig. 6A). We found that exposure to blue light (~ 1 s) at ~ 27 hpf triggered motor behaviors in both wild-type and *touché* mutant embryos positive for eYFP expression (Fig. 6B). In contrast, exposure to red light failed to evoke motor behaviors in either wild-type or *touché* mutant embryos positive for eYFP expression (Fig. 6C). As a control, embryos expressing eGFP within the same neurons failed to respond to blue light exposure. Thus the reaction to blue light required the injection of the ChR2-eYFP construct. These findings indicate that transmission of electrical signals downstream of action potential generation in sensory neurons appears present, and capable of activating motor behaviors within *touché* mutants.

Excitable properties of *touché* mutant sensory neurons are normal

Previously the development of ionic currents in zebrafish RB neurons were examined (Ribera and Nüsslein-Volhard, 1998), wherein the maturation of an overshooting action potential in sensory neurons was suggested to underlie the development of touch responsiveness. This hypothesis was supported by the examination of sensory neuron membrane properties from the touch-unresponsive mutant *macho*, which revealed that *macho* mutants fail to develop overshooting action potentials despite the normal development of other ionic currents. Based on these findings the excitable properties of *touché* RB neurons were examined *in vivo* using a preparation wherein the skin and muscle contralateral to target RB neurons was removed leaving the peripheral neurites intact (Fig. 7A). Using this preparation we found that RB neurons from both wild-type and *touché* mutants initiate action potentials in response to depolarizing current injections to the cell body (Fig. 7B). When compared wild-type and *touché* mutant RB neurons were found to exhibit similar resting membrane potentials, action potential thresholds, and amplitudes of overshoot and undershoot (Fig. 7C).

Next a bipolar stimulating probe, attached to a piezoelectric motor, was placed upon eGFP-positive neurites ~ 100 μm from the cell body in the stable transgenic line described above (Fig. 5). This approach allowed for the electrical and mechanical stimulation (see below) of the same neurite belonging to one RB neuron. In both wild-type and *touché* mutant RB neurons, depolarization of the peripheral neurite evoked action potentials detectable within the cell body (Fig. 7B). A similar stimulus applied ~ 15 μm rostral or caudal to the peripheral neurite failed to activate sensory neurons indicating that the bipolar stimulating probe was focally exciting neurites. When again compared wild-type and

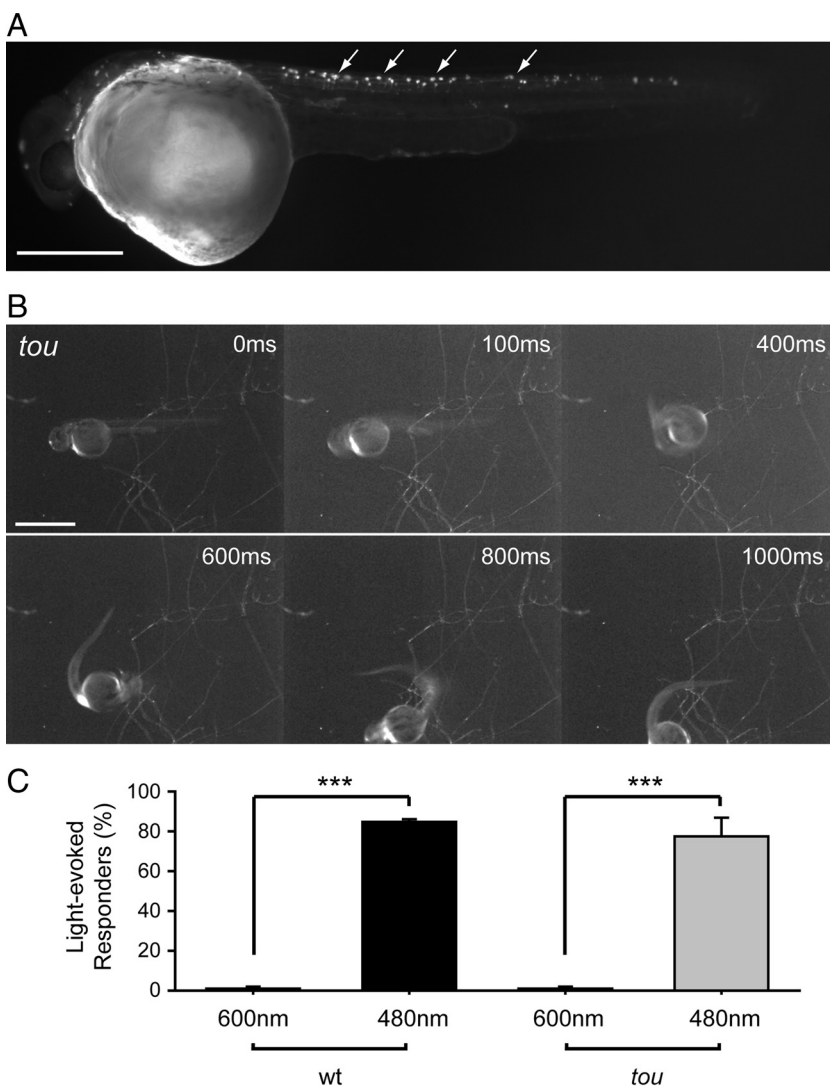


Figure 6. Light-evoked activation of motor behaviors in *touché* mutants. **A**, Lateral view of a 28 hpf *touché* mutant embryo with several RBs positive for expression of ChR2-eYFP (arrows). Scale bar, 200 μm . **B**, Responsiveness of a *touché* mutant embryo to blue light (480 nm) exposure. Scale bar, 500 μm . **C**, Average responsiveness of embryos to red light (600 nm) and blue light ($n = 30$ from 3 clutches) exposure. *** $p \leq 0.001$.

touché mutant RB neurons were found to exhibit similar action potential thresholds, and generated action potentials with similar amplitudes of overshoot and undershoot (Fig. 7C). Thus the lack of responsiveness to light touch in *touché* mutants cannot be explained by a difference in the excitability of *touché* mutant sensory neurons, or by a breakdown in electrical signals from the peripheral neurites to the cell body.

touché mutants lack sensory neurons with generator potentials

To examine whether tactile stimuli delivered to the peripheral neurite could evoke action potentials detectable within the cell body in *touché* mutants the bipolar stimulating probe was driven into the peripheral neurite with a piezoelectric motor. Previously the movement of probes with the piezoelectric motor was shown to be controllable on the μm level, with movements being completed within hundreds of microseconds (Moffatt and Hume, 2007). We found that in wild-type RB cells, wherein electrical stimulation of the peripheral neurite-evoked action potentials detectable within the cell body (Fig. 7B), mechanical stimulation

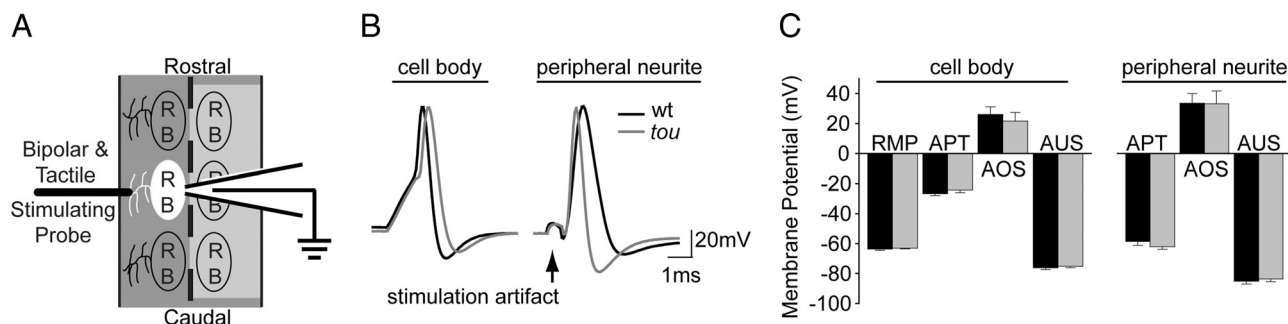


Figure 7. Electrical stimulation of peripheral neurites triggers action potentials within *touché* mutant RBs. **A**, Schematic of the *in vivo* recording preparation, which allows for electrical and mechanical stimulation of the same peripheral neurite. Dashed line indicates dorsal midline. Light gray area indicates the region in which the skin and muscle were removed to allow access to a contralateral RB cell body with an intact peripheral neurite (white). **B**, Depolarizing intracellular current injections (2 ms) to cell bodies (left panel) and extracellular stimulation (1 ms) of peripheral neurites (right panel). **C**, Analysis of resting membrane potential (RMP), action potential thresholds (APT), amplitude of overshoots (AOS), amplitude of undershoots (AUS) in response to depolarizing current stimulation of cell bodies and peripheral neurites for both wild-type ($n = 19$) and *touché* mutants ($n = 16$).

also triggered action potentials detectable within the cell body ($n = 19/19$; Fig. 8A). A closer examination revealed that RB cells in wild-type larvae could be subdivided into two groups: those possessing generator potentials (type I, $n = 9/19$), and those wherein a generator potential was not observed (type II, $n = 10/19$; Fig. 8A). Employing the same stimulating technique in *touché* mutants, which had also responded to electrical stimulation of the peripheral neurite ($n = 16/16$), failed to uncover RB cells with generator potentials (type I, $n = 0/16$).

Generator potentials are graded membrane depolarizations induced in the termini of touch-sensitive neurons, which upon reaching sufficient amplitudes, trigger action potentials in sensory afferents. To examine whether the membrane depolarizations observed in zebrafish RB neurons in response to mechanical stimuli were generator potentials a series of subthreshold mechanical stimuli were delivered to the peripheral neurite of several RB neurons ($n = 6$). In response to increasing mechanical stimuli membrane depolarizations were found to be graded (Fig. 8B), and after normalizing for RB neuron input resistances (Fig. 8C) strongly correlated with displacement ($r^2 = 0.97$). Finally to ensure that the graded membrane depolarizations were not failed action potentials we applied tetrodotoxin to the recording chamber which prevented spiking ($n = 2$), but failed to block the graded membrane depolarizations indicating that the observed graded membrane depolarizations were in fact generator potentials. Collectively these findings suggest that the *touché* mutant phenotype results from a lack of sensory neurons with generator potentials, and implies that light touch in zebrafish is conveyed by mechanosensitive neurons with generator potentials.

Discussion

In a screen for novel touch-unresponsive zebrafish mutants we uncovered one mutant, subsequently name *touché*, which was unresponsive to light touch. Although rough mapping indicated that *touché* could be a new allele of *macho*, a previously identified touch-unresponsive mutant (Granato et al., 1996), pairwise crosses with *macho* carriers complemented the *touché* mutant phenotype. Thus *touché* represents a new touch-unresponsive mutant.

Upon closer examination of the *touché* mutant phenotype it was noted that *touché* mutants also lacked a stopping response, a behavior known to require input from trigeminal touch-sensitive neurons (Boothby and Roberts, 1992a,b). This finding suggested that the *touché* mutation might affect all mechanosensitive processes, however *touché* mutants were found to exhibit acoustic-

vestibular behaviors which rely on input from mechanosensitive hair cells. Coupled with the normal responsiveness of *touché* mutants to noxious stimuli (mustard oil and low pH) implies that the *touché* mutation affects behaviors dependent upon input from touch-sensitive neurons.

Potentially in support of a requirement for *touché* in the regulation of behaviors dependent upon input from touch-sensitive neurons were the findings that *touché* mutants swam for longer durations following electrical stimulation, and were more spontaneously active at 4 d, a time point wherein larvae are rather immobile and often found to be stuck to the sides of objects. These findings may reflect an absence of sensory feedback from mechanosensitive neurons such as those that innervate mucous cells which likely alert zebrafish larvae that they have encountered an object suitable for adherence similar to *Xenopus laevis* embryos (Boothby and Roberts, 1992a,b). Alternatively the increase in spontaneous activity in mutants could reflect the absence of an inhibitory influence of *touché* on the locomotor network which underlies swimming in zebrafish, or a requirement of sensory input in modulating locomotor network activity.

In an attempt to understand the contribution of *touché* to the activation of touch-evoked behaviors we first considered that the inability of *touché* mutants to respond to light touch could be the result of absent, or aberrant touch-sensitive neurons. However comparisons between wild-type and *touché* mutants revealed that mutants possessed a similar number of RB neurons per somite, trigeminal neurons, and extent of skin innervation by peripheral neurites. While these findings suggest that the mutant phenotype is the result of a functional loss of *touché* within touch-sensitive neurons a limitation of this comparison exists which stems from a general lack of knowledge concerning sensory neurons in zebrafish. Presently it is unknown whether zebrafish sensory neurons are a heterogeneous or homogenous population of mono or polymodal-sensitive neurons. Therefore while *touché* mutants have a similar overall number of sensory neurons, *touché* mutants could lack a subtype of sensory neuron responsive to light touch while having more of another type. A detailed analysis of sensory neuron responsiveness to various stimuli in zebrafish is needed to examine this possibility.

We next considered that *touché* might be required functionally within touch-sensitive neurons for the transduction of tactile stimuli to second order neurons. This requirement could be (but not limited to) within the mechanotransduction complex responsible for the transformation of tactile stimuli into an electri-

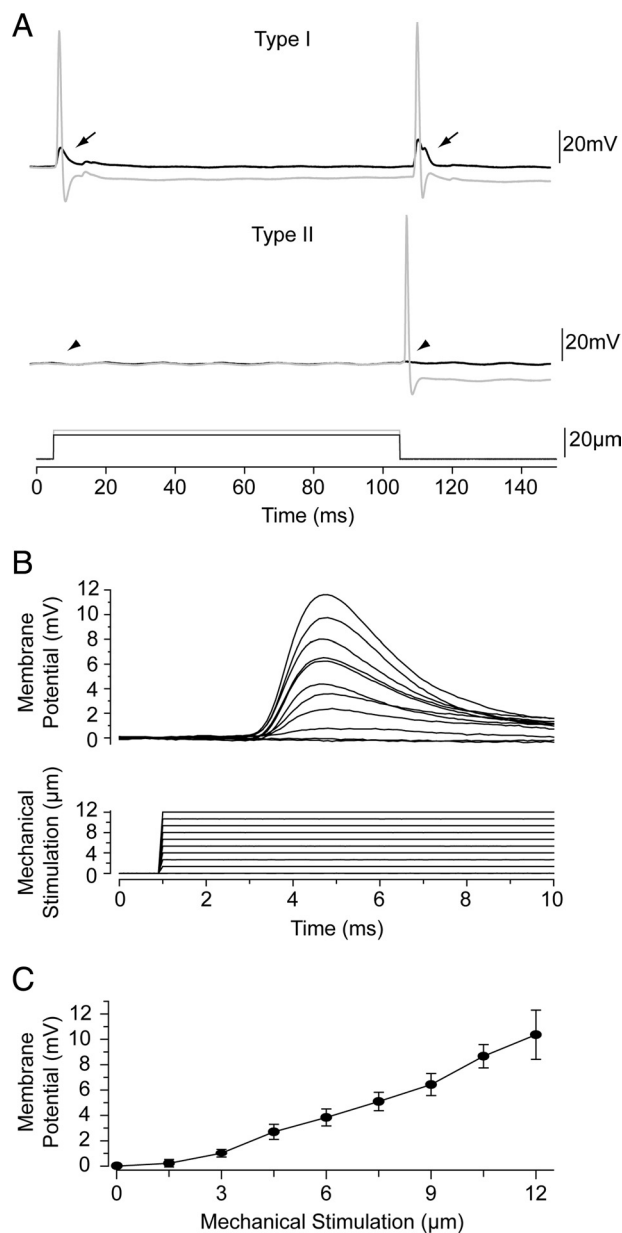


Figure 8. *touché* mutants lack sensory neurons with generator potentials. **A**, Top, In a subset of RB cells (type I, $n = 9/19$), a subthreshold mechanical stimulus (black) applied to the peripheral neurite results in a generator potential (arrows) at the onset and offset of the stimulus. In these RB cells, increasing the amplitude of stimuli (gray) triggers action potentials at the onset and the offset of the stimulus. Bottom, Other RB cells (type II; $n = 9/19$) activated by mechanical stimuli (gray) lack generator potentials (arrowheads) in response to subthreshold stimuli (black). **B**, Generator potentials activated in response to increasing mechanical stimuli. **C**, The amplitude of generator potentials correlates with the amplitude of mechanical stimuli ($n = 6$).

cal signal within touch-sensitive neurons, in neurites for the transmission of the action potentials from the peripheral neurite to the central synapse, or at the level of the central synapse in transmitter release. In an attempt to discern between these possibilities we attempted to drive motor behaviors in *touché* mutants optogenetically with channelrhodopsin-2. We found that wild-type and *touché* mutants expressing channelrhodopsin-2 in sensory neurons responded to blue light (480 nm) with motor behaviors. These findings indicate that *touché* mutant sensory neurons can activate second order neurons leading to motor behaviors, suggestive of a defect within sensory neuron activation.

To explore the activation of sensory neurons *in vivo* we developed and used a novel recording preparation which allowed for electrical and mechanical stimulation of the same peripheral neurite. This preparation revealed that the transduction of an electrical signal from the peripheral neurite to the cell body was intact in both wild-type and *touché* mutants. Furthermore tactile stimuli applied to the same neurite triggered action potentials detectable within the cell bodies of both wild-type and *touché* mutants. However, in contrast to wild-type RB cells, we did not observe any *touché* mutant RB cells wherein mechanically evoked action potentials exhibited generator potentials (type I).

The generator potentials observed in type I zebrafish RB neurons are rapidly adapting with activation at both the onset and offset of a stimulus. When combined with the apparent morphology of zebrafish RB neurons, this suggests that the type I cutaneous mechanoreceptors described here are most similar to mammalian Aδ “free nerve endings,” which in addition to mediating tactile stimuli are thought to communicate thermo and nociceptive stimuli. In support of this comparison are reports suggesting that RB neurons are polymodal in nature, as they express multiple receptors (Kucenas et al., 2003; Prober et al., 2008), which are known to participate in the integration of various sensory stimuli in other vertebrates (Cockayne et al., 2000, 2005; Bautista et al., 2006; Kwan et al., 2006). In contrast, type II neurons which lack generator potentials may represent nociceptive neurons which are responding indirectly to tissue damage rather than directly to tactile stimuli. Further experiments involving calibrated low force probes and conduction velocity assays in zebrafish will provide insight into the comparison with mammalian sensory neurons.

Collectively the findings presented here indicate that *touché* is required either developmentally for the differentiation/retention of light touch-sensitive neurons, or functionally within a subset of touch-sensitive neurons for the conversion tactile stimuli into action potentials via a generator potential dependent process. Discerning between these two possibilities will require a better understanding of the zebrafish sensory neuron population, insights into the genetic pathways governing the development of sensory neuron subtypes, and ultimately the molecular identification of the *touché* locus.

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